

Re-labeling ImageNet: from Single to Multi-Labels, from Global to Localized Labels

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Abstract

ImageNet has been arguably the most popular image classification benchmark, but it is also the one with a significant level of label noise. Recent studies have shown that many samples contain multiple classes, despite being assumed to be a single-label benchmark. They have thus proposed to turn ImageNet evaluation into a multi-label task, with exhaustive multi-label annotations per image. However, they have not fixed the training set, presumably because of a formidable annotation cost. We argue that the mismatch between single-label annotations and effectively multi-label images is equally, if not more, problematic in the training setup, where random crops are applied. With the single-label annotations, a random crop of an image may contain an entirely different object from the ground truth, introducing noisy or even incorrect supervision during training. We thus re-label the ImageNet training set with multi-labels. We address the annotation cost barrier by letting a strong image classifier, trained on an extra source of data, generate the multi-labels. We utilize the pixel-wise multi-label predictions before the final pooling layer, in order to exploit the additional location-specific supervision signals. Training on the re-labeled samples results in improved model performances across the board. ResNet-50 attains the top-1 classification accuracy of **78.9%** on ImageNet with our localized multi-labels, which can be further boosted to **80.2%** with the CutMix regularization. We show that the models trained with localized multi-labels also outperforms the baselines on transfer learning to object detection and instance segmentation tasks, and various robustness benchmarks. The re-labeled ImageNet training set, pre-trained weights, and the source code are available at https://github.com/naver-ai/relabel_imagenet.

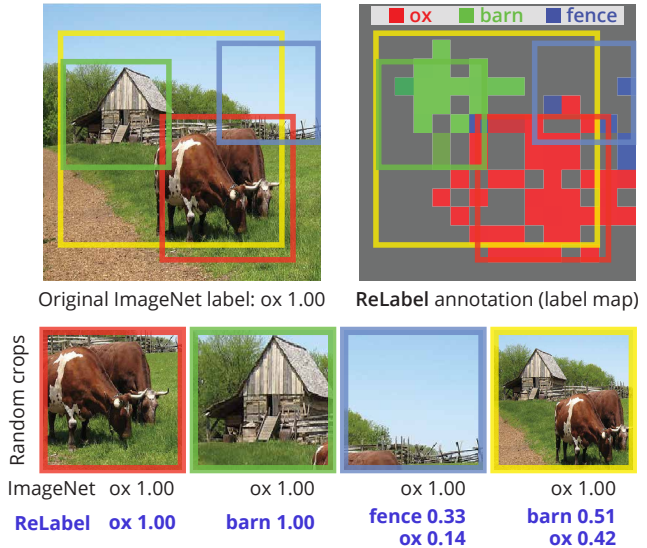


Figure 1. **Re-labeling ImageNet training data.** Original ImageNet annotation is a single label (“ox”), whereas the image contains multiple ImageNet categories (“ox”, “barn”, and “fence”). Random crops of an image may contain an entirely different object category from the global annotation. Our method (**ReLabel**) generates location-wise multi-labels, resulting in cleaner supervision per random crop.

1. Introduction

The ImageNet dataset [42] has been at the center of modern advances in computer vision. Since the introduction of ImageNet, image recognition models based on convolutional neural networks have made quantum jumps in performances [30, 45, 16]. Improving the model performance on ImageNet is seen as a litmus test for the general applicability of the model and the transfer learning performances on downstream tasks [28, 60].

ImageNet, however, turns out to be noisier than one would expect. Recent studies [46, 53, 2, 43] have shed light on an overlooked problem with ImageNet that a significant portion of the dataset is composed of images with multi-

ple possible labels. This contradicts the underlying assumption that there is only a single object class per image: the evaluation metrics penalize any prediction beyond the single ground-truth class. Thus, researchers have refined the ImageNet validation samples with multi-labeling policy using human annotators [2, 43], and proposed new multi-label evaluation metrics. Under these new evaluation schemes, recent state-of-the-art models [56, 52] that seem to have surpassed the human level of recognition have been found to fall short of the human performance level.

The mismatch between the multiplicity of object classes per image and the assignment of single labels results in problems not only for evaluation, but also for training: the supervision becomes noisy. The widespread adoption of *random crop* augmentation [48] aggravates the problem. A random crop of an image may contain an entirely different object from the original single label, introducing potentially wrong supervision signals during training, as in Figure 1.

The random crop augmentation makes supervision noisy not only for images with multiple object classes. Even for images with a single object class, the random crop often contains no foreground object. It is estimated that, under the standard ImageNet training setup¹, 8% of the random crops have no overlap with the ground truths. Only 23.5% of the random crops have the intersection-over-union (IoU) measure greater than 50% with the ground truth boxes (see Figure 2). Training a model on ImageNet inevitably involves a lot of noisy supervision.

Ideally, for each training image, we want a human annotation telling the model (1) the full set of classes present (multi-label) and (2) where each object is located (localized label). One such format would be a dense pixel labeling $L \in \{0, 1\}^{H \times W \times C}$ where C is the number of classes, as done for semantic segmentation ground truths. However, it is hardly scalable to collect even just the multi-label annotations for the 1.28 million ImageNet training samples. It took more than three months for five human experts (authors of [43]) to label mere 2,000 images.

In this paper, we propose a re-labeling strategy, **ReLabel**, to obtain pixel-wise labeling $L \in \mathbb{R}^{H \times W \times C}$, which are both multi-labels and localized labels, on the ImageNet training set. We use strong classifiers trained on external training data to generate those labels. The predictions before the final pooling layer have been used. We also contribute a novel training scheme, **LabelPooling**, for training classifiers based on the dense labels. For each random crop sample, we compute the multi-label ground truth by pooling the label scores from the crop region. ReLabel incurs only a one-time cost for generating the label maps per dataset, unlike *e.g.* Knowledge Distillation [22] which involves one forward pass per training iteration to generate the supervision. Our LabelPooling supervision adds only

¹A random crop is sampled from 8% to 100% of the entire image area.

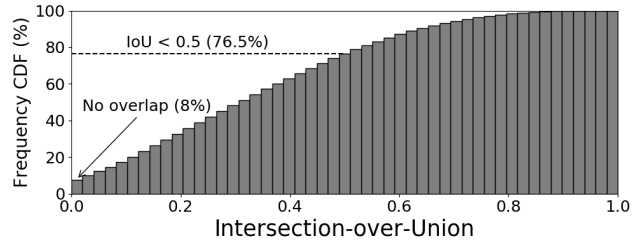


Figure 2. **Cumulative distribution of Intersection-over-Union (IoU)** between the random crops and ground-truth bounding boxes. We sample 100 random crops per image on the ImageNet validation set (50K images).

a small amount of computational cost on the usual single-label cross-entropy supervision.

We present an extensive set of evaluations for various model architectures trained with ReLabel on multiple datasets and tasks. On ImageNet classification, training ResNet-50 with ImageNet ReLabel has achieved a top-1 accuracy of **78.9%**, a **+1.4 pp** gain over the baseline model trained with the original labels. The accuracy of ResNet-50 reaches **80.2%** by employing the CutMix regularization on top, a new state-of-the-art performance on ImageNet to the best of our knowledge. Models trained with ReLabel have also consistently improved accuracies on ImageNet multi-label evaluation metrics proposed by [2, 43]. ReLabel and LabelPooling result in consistent improvements for transfer learning experiments, including the object detection and instance segmentation tasks on COCO and fine-grained classifications tasks. We further test LabelPooling on the multi-label classification task on COCO. Finally, we show that models trained with ReLabel are more resilient to test-time perturbations, as will be verified through experiments on several robustness benchmarks.

2. Related Works

We start this section by introducing prior works discussing the issues with ImageNet labels. We then discuss a few other research areas that share similarities with our approach. For each area, we describe the key differences from our approach.

Labeling issues in ImageNet. ImageNet [42] has effectively served as the standard benchmark for the image classifiers: “methods live or die by their performance on this benchmark”, as argued by Shankar *et al.* [43]. The reliability of the benchmark itself has thus come to be the subject of careful research and analysis. As with many other datasets, ImageNet contains much label noise [54, 40]. One of the most persistent and systematic types of label error on ImageNet is the erroneous single labels [46, 43, 53, 2], referring to the cases where only one out of multiple present

	multi-label	local label	efficient
Original ImageNet training	✗	✗	✓
Knowledge distillation	✓	✓	✗
ReLabel & LabelPooling (ours)	✓	✓	✓

Table 1. **What are the differences?** Comparison among the training options on ImageNet.

categories is annotated. Such errors are prevalent, as ImageNet contains many images with multiple classes. Shankar *et al.* [43] and Beyer *et al.* [2] have identified three subcategories for the erroneous single labels: (1) an image contains multiple object classes, (2) there exist multiple labels that are synonymous or hierarchically including the other, and (3) inherent ambiguity in an image makes multiple labels plausible. Those studies have refined the validation set labels into multi-labels to establish a truthful and fair evaluation of models on effectively multi-label images. The focus of [43], however, has been only the validation, not training. [2] has introduced a clean-up scheme to remove training samples with potentially erroneous labels by validating them with predictions from a strong classifier. Our work focuses on the clean-up strategy for the ImageNet training labels. Like [2], we utilize strong classifiers to clean up the training labels. Unlike [2], we *correct* the wrong labels, not *remove*. Our labels are also given per region. In our experiments, we show that our scheme results in improved performance compared to [2].

Knowledge distillation. Knowledge distillation (KD) [22] also utilizes machine supervisions generated by the “teacher” network. Studies on KD have enriched and diversified the options for the teacher, such as feature map distillation [61, 21, 20], relation-based distillation [37, 51], ensemble distillation [44, 65], or iterative self-distillation [10, 58, 56]. While those studies pursue stronger forms of supervision, none of them have considered a strong, state-of-the-art network as a teacher because it makes the KD supervision far heavier and impractical. With the random crop augmentation in place, every training iteration would involve a forward pass through the strong yet heavy teacher. LabelPooling is similar in that the model is trained with machine supervision, but is more efficient. LabelPooling supervises a network with pre-computed label maps, rather than generating the label on the fly through the teacher for every random crop during training. The key advantages of ReLabel and LabelPooling against the original training and KD are summarized in Table 1. We present experiments comparing ours against the state-of-the-art KD approaches.

Training tricks for ImageNet. Data augmentation is a simple yet powerful strategy for ImageNet training. The standard augmentation setting includes random cropping, flipping, and color jittering, as used in [13, 11, 24, 48, 60, 52].

In particular, the random crop augmentation, which crops random coordinates in an image and resize to a fixed size, is indispensable for a reasonable performance on ImageNet. Our work considers localized labels that make the supervision provided for each random crop region more sensible. There are additional training tricks for training classifiers [62, 60, 11, 25, 9] that are orthogonal to our re-labeled training data. We show that those tricks can be combined with our re-labeling for improved performances.

3. Method

We propose a re-labeling strategy **ReLabel** to obtain pixel-level ground truth labels on the ImageNet training set. The label maps have two characteristics: (1) multi-class labels and (2) localized labels. The labels maps are obtained from a machine annotator: a state-of-the-art image classifier trained on an extra source data. We describe how to obtain the label maps and present a novel training framework, **LabelPooling**, to train image classifier using such localized multi-labels.

3.1. Re-labeling ImageNet

We obtain dense ground truth labels from a *machine annotator*, a state-of-the-art classifier that has been pre-trained on a super-ImageNet scale (*e.g.* JFT-300M [47] or InstagramNet-1B [35]) and fine-tuned on ImageNet to predict ImageNet classes. Predictions from such a model are arguably close to human predictions [2]. Since training the machine annotators requires an access to proprietary training data [47, 35] and hundreds of GPU or TPU days, we have adopted the open-source trained weights as the machine annotators. We show the comparison of different available machine annotators later in Section 3.3.

We remark that while the machine annotators are trained with single-label supervision (softmax cross-entropy loss) on ImageNet, they still tend to make multi-label predictions for images with multiple categories. As an illustration, consider an image x with two correct categories 0 and 1. Assume that the model is fed with both $(x, y = 0)$ and $(x, y = 1)$ equal number of times during training, with those noisy labels. Then, the cross-entropy loss is given by $-\frac{1}{2}(\sum_k y_k^0 \log p_k(x) + \sum_k y_k^1 \log p_k(x)) = -\sum_k \frac{y_k^0 + y_k^1}{2} \log p_k(x)$ where y^c is the one-hot vector with 1 at index c and $p(x)$ is the prediction vector for x . Note that the minimal value for the function $-\sum_k q_k \log p_k$ with respect to p is taken at $p = q$. Thus, in this example, the model minimizes the loss by predicting $p(x) = (\frac{1}{2}, \frac{1}{2})$. Thus, if there exist much label noise in the dataset, a model trained with the single-label cross-entropy loss tends to predict multi-label outputs.

As an additional benefit of obtaining labels from a classifier, we consider extracting the location-specific labels.

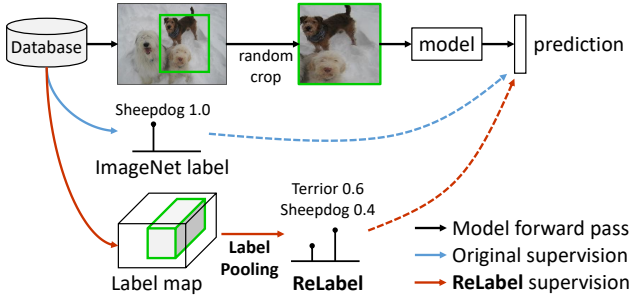


Figure 3. **Illustration of LabelPooling.** Original ImageNet supervision is single-label (“Sheepdog”). LabelPooling trains the model with ReLabel, localized multi-labels, (“Sheepdog” and “Terror”) based on the crop region.

We remove the *global average pooling* layer of the classifier and turn the following linear layer into a 1×1 convolutional layer, thereby turning the classifier into a fully-convolutional network [64, 33]. The output of the model then becomes $f(x) \in \mathbb{R}^{W \times H \times C}$. We use the output $f(x)$ as our *label map* annotations $L \in \mathbb{R}^{W \times H \times C}$. We present the detailed procedure to obtain label maps the examples in Appendix B.

3.2. Training a Classifier with Dense Multi-labels

Having obtained the dense multi-labels $L \in \mathbb{R}^{W \times H \times C}$ as above, how do we train a classifier with them? For this, we propose a novel training scheme, LabelPooling, that takes the localized ground truths into account. We show the difference between LabelPooling and the original ImageNet training in Figure 3. In a standard ImageNet training setup, the supervision for the randomly crop is given by the single label ground truth given per image. On the other hand, LabelPooling loads a pre-computed label map and conducts a regional pooling operation on the label map corresponding to the coordinates of the random crop. We adopt the RoIAlign [15] regional pooling approach. Global average pooling and softmax operations are performed on the pooled prediction maps to get a multi-label ground-truth vector in $[0, 1]^C$ with which the model is trained. We use the cross-entropy loss. Code-level implementation of our training scheme is presented in Appendix A.

3.3. Discussion

So far we have introduced our labeling strategy and the supervision scheme using the label maps. We study the space and time consumption for our approach and examine design choices.

Space consumption. We utilize EfficientNet-L2 [56] as the machine annotator whose input resolution is 475×475 and the resulting label map dimension is $L \in \mathbb{R}^{15 \times 15 \times 1000}$. Saving the entire label maps for all classes will require more

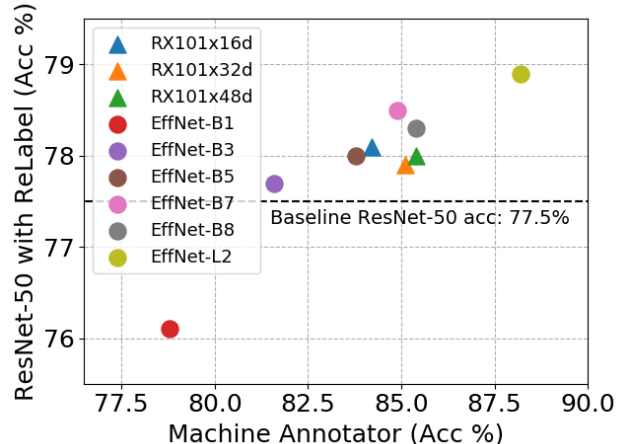


Figure 4. **Machine annotators.** We plot the top-1 accuracy of ResNet-50 trained with ReLabel, where ReLabel is generated by various machine annotators.

than 1 TB of storage: (1.28×10^6) images $\times (15 \times 15 \times 1000)^{\dim/\text{image}} \times 4^{\text{bytes}/\text{dim}} \approx 1.0$ TB. Fortunately, for each image, pixel-wise predictions beyond a few top- k classes are essentially zero. Hence, we save the storage space by storing only the top-5 predictions per image, resulting in 10 GB of label map data. This corresponds to only 10% additional space on top of the original ImageNet data.

Time consumption. ReLabel requires a one-time cost for forward passing the ImageNet training images through the machine annotator. This procedure takes about 10 GPU-hours, which is only 3.3% of the entire train time for ResNet-50 (328 GPU-hours²). For each training iteration, LabelPooling performs the label map loading and regional pooling operations on top of the standard ImageNet supervision, which leads to only 0.5% additional training time. Note that ReLabel is much more computationally efficient than knowledge distillation which requires a forward pass through the teacher at every iteration. For example, KD with EfficientNet-B7 teacher takes more than four times the original training time.

Which machine annotator should we select? Ideally, we want the machine annotator to provide precise labels on training images. For this we consider ReLabel generated by a few state-of-the-art classifiers EfficientNet-{B1,B3,B5,B7,B8} [50], EfficientNet-L2 [56] trained with JFT-300M [47], and ResNeXT-101_32x{32d,48d} [57] trained with InstagramNet-1B [35]. We train ResNet-50 with the above label maps from diverse classifiers. Note that ResNet-50 achieves the top-1 validation accuracy of 77.5% when trained on vanilla single labels. We show the results in Figure 4. The performance of the target model

²300 epochs on four NVIDIA V100 GPUs.

Variants	ImageNet top-1 (%)
ReLabel (localized mutli-labels)	78.9
Localized single labels	78.4 (-0.5)
Global multi-labels	78.5 (-0.4)
Global single labels	77.5 (-1.4)
Original ImageNet labels	77.5 (-1.4)

Table 2. **Factor analysis of ReLabel.** Results when either or both of the multi-labelness and localizability properties are removed from ReLabel.

overall follows the performance of the machine annotator. When the machine supervision is not sufficiently strong (e.g., EfficientNet-B1), the trained model shows a severe performance drop (76.1%). We choose EfficientNet-L2 as the machine annotator that has led to the best performance for ResNet-50 (78.9%) in the rest of the experiments.

Factor analysis of ReLabel. ReLabel is both multi-label and pixel-wise. To examine the necessity of the two properties, we conduct an experiment by ablating each of them. We consider the *localized single labels* by taking `argmax` operation instead of `softmax` after the `RoIAlign` regional pooling, resulting in $L_{loc, single} \in \{0, 1\}^C$. For *global multi-labels*, we take the global average pooling, instead of the `RoIAlign`, over the label map, resulting in the label $L_{glob, multi} \in [0, 1]^C$. Finally, by first performing the global average pooling and then performing `argmax`, we obtain the *global single-labels*, $L_{glob, single} \in \{0, 1\}^C$. Note that $L_{glob, single} \in \{0, 1\}^C$ labels have the same format as the original ImageNet labels, but are machine-generated.

The results for those four variants are in Table 2. We observe that from the ReLabel performance of 78.9%, the removal of multi-labels and localized labels results in -0.5 pp and -0.4 pp drops, respectively. When both are missing, there is a significant -1.4 pp drop. We thus argue that both ingredients are indispensable for a good performance. Note also that the global, single labels generated by a machine do not bring about any gain compared to the original ImageNet labels. This further signifies the importance of the aforementioned properties to benefit maximally from the machine annotations.

Confidence of ReLabel supervision. We study the confidence of ReLabel supervisions at different simulated levels of overlap between the random crop and the ground-truth bounding box. We draw 5M random crop samples as done for Figure 2. We measure the confidence for the ReLabel’s supervision in terms of the maximum class probability of the pooled label (i.e., confidence = $\max_c L(c)$ where $L \in [0, 1]^C$). The results are shown in Figure 5. The averaged degree of supervision of ReLabel overall follows the degree of object existence, in particular, with small over-

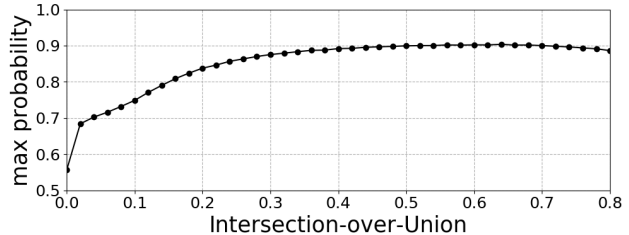


Figure 5. **ReLabel confidence versus GT overlap.** We plot the relationship between the confidence level for ReLabel pooled from the crop regions and the their overlap (IoU) with the ground truth boxes.

laps with object region (IoU < 0.4). For example, when IoU is zero (i.e., random crops are outside the object region), the label confidence is below 0.6, providing some uncertainty signals for the trained model.

4. Experiments

We present various experiments where we apply our labeling and training schemes for localized multi-label training. We first show the effectiveness of ReLabel on ImageNet classification with various network architectures and evaluation metrics, including the recently proposed multi-label evaluation metrics (Section 4.1). Next, we show the transfer-learning performances for models trained with ReLabel when they are fine-tuned for object detection, instance segmentation, and fine-grained classification tasks (Section 4.2). We show that ReLabel improves the performances also for models on COCO multi-label classification tasks (Section 4.3). All experiments were implemented and evaluated on NAVER Smart Machine Learning (NSML) [26] platform with PyTorch [39]. The re-labeled ImageNet training set, pre-trained weights, and the source code are available at https://github.com/naver-ai/relabel_imagenet.

4.1. ImageNet Classification

We evaluate ReLabel strategy on the ImageNet-1K benchmark [42] containing 1.28 million training images and 50,000 validation images of 1,000 object categories. We use standard data augmentation such as random cropping, flipping, color jittering, as in [13, 11, 24, 48, 60, 52] for all the models considered. We have trained the models with SGD for 300 epochs with the initial learning rate 0.1 and the cosine learning rate scheduling without restarts [34]. The batch size and weight decay are set to 1,024 and 0.0001, respectively.

Comparison against other label manipulations. We compare ReLabel against prior methods that directly adjust the ImageNet labels. Label smoothing [49] assigns a slightly

Network	Supervision	ImageNet	ImageNetV2 [40]	ReaL [2]	Shankar <i>et al.</i> [43]
		single-label	single-label	multi-label	multi-label
ResNet-50	Original	77.5	79.0	83.6	85.3
ResNet-50	Label smoothing ($\epsilon=0.1$) [49]	78.0	79.5	84.0	84.7
ResNet-50	Label cleaning [2]	78.1	79.1	83.6	85.2
ResNet-50	ReLabel	78.9	80.5	85.0	86.1

Table 3. **ImageNet classification.** Results with different types of supervision. We report performances on the single-label benchmarks (ImageNet validation set and ImageNetV2 [40]) and multi-label benchmarks (ReaL [2] and Shankar *et al.* [43]).

Architecture	Resources		Supervision	
	Params	Flops	Vanilla	ReLabel
ResNet-18	11.7M	1.8B	71.7	72.5 (+0.8)
ResNet-50	25.6M	3.8B	77.5	78.9 (+1.4)
ResNet-101	44.7M	7.6B	78.1	80.7 (+2.6)
EfficientNet-B0	5.3M	0.4B	77.4	78.0 (+0.6)
EfficientNet-B1	7.8M	0.7B	79.2	80.3 (+1.1)
EfficientNet-B2	9.2M	1.0B	80.3	81.0 (+0.7)
EfficientNet-B3	12.2M	1.8B	81.7	82.5 (+0.8)
ReXNet ($\times 1.0$)	4.8M	0.4B	77.9	78.4 (+0.5)

Table 4. **ReLabel on multiple architectures.** Validation top-1 results when supervised with the original labels (Vanilla) and ReLabel.

weaker weight on the foreground class ($1 - \epsilon$) and distributes the remaining weight ϵ uniformly across background classes. Label cleaning by Beyer *et al.* [2] prunes out all training samples where the ground truth annotation does not agree with the prediction of a strong teacher classifier. For this, we use the list of clean sampled provided by the authors [2] with our own training setting. We conducted the above label manipulation methods and ReLabel on ResNet-50. Results are given in Table 3. We measure the single-label accuracies on ImageNet validation and ImageNetV2 (Top-Images [40]³). We show multi-label accuracies on two versions: ReaL [2] and Shankar *et al.* [43]. The metrics are identical: $\frac{1}{N} \sum_{n=1}^N 1(\arg \max f(x_n) \in y_n)$, where $1(\cdot)$ is the indicator function and $\arg \max f(x_n)$ is the top-1 prediction for a model f . The ground-truth multi-label for image x_n is given as a set y_n . The difference between the metrics lies in the ground-truth multi-label annotation. We observe that ReLabel consistently achieves the best performance over all the metrics. We obtain 78.9% validation accuracy with +1.4 pp gain from the original labels, while the label smoothing and label cleaning boost only +0.5 pp and +0.6 pp, respectively. On ImageNetV2, ReaL, and

³Results on ImageNetV2 “MatchedFrequency” and “Threshold 0.7” are in Appendix C

Model	ImageNet top1 (%)
ResNet-50	77.5
+ ReLabel	78.9 (+1.4)
+ ReLabel + CutMix	80.2 (+2.7)
+ ReLabel + CutMix + Extra data	81.2 (+3.7)
ResNet-101	78.1
+ ReLabel	80.7 (+2.6)
+ ReLabel + CutMix	81.6 (+3.5)

Table 5. **Towards the SOTA.** ReLabel with additional training tricks. “Extra data” refers to the ImageNet-21k dataset.

Shankar *et al.* metrics, ReLabel achieves 80.5%, 85.0%, and 86.1% accuracies, where the gains are +1.5 pp, +1.4 pp, and +0.8 pp, respectively. It is notable that only ReLabel achieves remarkable boosts on the multi-label benchmarks. Label smoothing and cleaning shows only marginal gains or even worse multi-label accuracies (*e.g.* label cleaning results in a 0.1 pp worse result on Shankar *et al.*). We confirm that ReLabel improves the performances of image classifiers and that it helps models truly learn to make better multi-label predictions.

Results on various network architectures. We have trained various architectures with ReLabel to show that ReLabel is applicable to a wide range of networks with different training recipes. We consider ResNet-18, ResNet-101, EfficientNet-{B0,B1,B2,B3} [50], and ReXNet [14]. Training details to make the best performance out of EfficientNet models [50] are different from our base setting; we describe them in Appendix D.1. We follow the original paper’s training details for ReXNet [14]. Results are shown in Table 4. ReLabel consistently enhances the performance of various network architectures. The 81.7% accuracy of EfficientNet-B3 is further improved to 82.5% with ReLabel.

State-of-the-art performance. ReLabel is complementary to many other training tricks used for achieving the best model performances. For example, we combine a strong regularizer CutMix [60] with ReLabel. CutMix mixes two training images via cut-and-paste manner and likewise mixes the labels. To use it with ReLabel, we perform Cut-

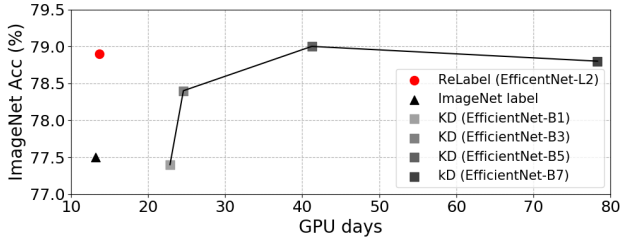
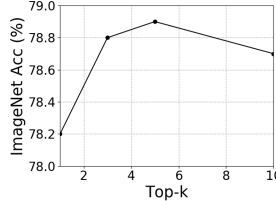


Figure 6. **Comparison against knowledge distillation.** We plot ImageNet top-1 accuracies against the required training time for ReLabel and knowledge distillation (KD) approaches.

Mix on the randomly cropped images. The pooled labels are then mixed according to the CutMix algorithm. We set the hyper-parameter of CutMix α to 1.0. We show the results in Table 5. ReLabel with CutMix achieves the state-of-the-art ImageNet top-1 accuracies of **80.2%** and **81.6%** for the ResNet-50 and ResNet-101 backbones. On top of this, we further consider using the extra training data based on the ImageNet-21K dataset [8]: 14M images with 21K categories. Unlike the previous work utilizing the ImageNet-21K [27] with their original single-class labels over 21K categories, we perform ReLabel on them to generate multi-labels over the 1K classes. We then sub-sample 4M training data from the entire 14M training images by balancing the top-1 class distributions, as done in [57]. Training with this extra data and CutMix on top of ReLabel boosts the accuracy of ResNet-50 to **81.2%**. In summary, ReLabel is a practical addition to existing training tricks that consistently improves the backbone performances.

Comparison against knowledge distillation. We compare ReLabel against knowledge distillation (KD) [22] in terms of the performance and training time costs. We train ResNet-50 with EfficientNet teachers: EfficientNet-{B1,B3,B5,B7}; we have not considered performing KD with EfficientNet-L2 as it would take 160 GPU days, beyond our computational capacity. Training details for KD are in Appendix D.2. Figure 6 shows the results. We plot the target model’s performance versus the required number of GPU days. KD with smaller teacher variants (EfficientNet-{B1,B3}) shows worse top-1 accuracies than ReLabel at higher training costs. For larger teachers (EfficientNet-{B5,B7}), KD achieves comparable performances with ReLabel (e.g. 79.0% for KD with B7 and 78.8% for ReLabel). However, they require 41 and 78 GPU days to train, compared to mere 13.6 using ReLabel. ReLabel-based training is almost as fast as the original training.

Storage-performance trade off. We study the trade off between the storage space for the label maps and the model performance. ReLabel only saves top- k prediction maps for



ImageNet top1 (%)	
Baseline	77.5
ReLabel	78.9
16-bit label map	78.8
8-bit label map	78.6

Table 6. **Storage versus performance.** How much performance do we lose by trying to cut storage space?

Models	FGSM	ImageNet-A	ImageNet-C
ResNet-50	25.7	4.9	27.9
+ ReLabel	31.3 (+5.6)	7.1 (+2.2)	28.1 (+0.2)

Table 7. **Robustness.** Impact of ReLabel on FGSM [12], ImageNet-A [18], and ImageNet-C [17] benchmarks.

the interest of efficient storage, where the default k value is 5. We explore $k \in \{1, 3, 5, 10\}$. We also study the impact of quantization levels for label maps: 16-bit and 8-bit floating point, instead of the default 32-bit floating point. The results are in Table 6. ReLabel achieves a good performance-efficiency trade-off when $k = 5$. Quantizing label maps tend to yield only small performance drops (-0.1 pp to -0.3 pp). When storage space is a crucial constraint, we advise users to adopt labels maps of coarser formats.

Combination with original labels. When we combine ReLabel’s annotation $L_{\text{ours}} \in [0, 1]^C$ with the original label $L_{\text{gt}} \in \{0, 1\}^C$ as $0.5L_{\text{ours}} + 0.5L_{\text{gt}}$, the performance degrades from 78.9% to 78.3% accuracy on ImageNet. They do not seem to make a good combination.

Robustness. We evaluate the robustness of ReLabel-trained models against test-time perturbations. We consider adversarial and natural perturbations: FGSM [12], ImageNet-A [18], and ImageNet-C [17]. FGSM introduces one-step adversarial perturbations on images, while ImageNet-A samples consistent of common failure cases for modern image classifiers. ImageNet-C consists of 15 different types of natural perturbations. Results are in Table 7. We observe that ReLabel consistently improves the resilience of models on adversarial and natural perturbations.

ReLabel examples on ImageNet. We present examples generated by ReLabel during ImageNet training in Appendix E. As shown in the examples, ReLabel can generate location-specific multi-labels with more precise supervision than the original ImageNet labels.

4.2. Transfer Learning

Apart from serving as the standard benchmark, ImageNet has contributed to the computer vision research and engineering with its suite of pre-trained models. When the

	Food-101 [3]	Stanford Cars [29]	DTD [6]	FGVC Aircraft [36]	Oxford Pets [38]
ResNet-50 (Baseline)	87.98	92.64	75.43	85.09	93.92
ResNet-50 (ReLabel -trained)	88.12	92.73	75.74	88.89	94.28

Table 8. **Fine-grained classification.** Performance on five tasks where the model starts either from weights regularly pre-trained on ImageNet or from weights pre-trained via ReLabel.

	Faster-RCNN	Mask-RCNN	
	bbox AP	bbox AP	mask AP
ResNet-50 (Baseline)	37.7	38.5	34.7
ResNet-50 (ReLabel -trained)	38.2	39.1	35.2

Table 9. **Detection and instance segmentation.** Transfer learning performances for Faster-RCNN [41] and Mask-RCNN [15] on COCO dataset [32].

target task has only a small number of annotated data, transfer learning from the ImageNet pre-training usually helps [28]. We examine here whether the ReLabel-induced improvements on the ImageNet performances transfer to various downstream tasks. We present the results of 5 fine-grained classification tasks and the object detection and instance segmentation tasks on COCO with models pre-trained on ImageNet with ReLabel.

Fine-grained classification tasks. We evaluate ReLabel-pretrained ResNet-50 on five fine-grained classification tasks: Food-101 [3], Stanford Cars [29], DTD [6], FGVC Aircraft [36], and Oxford Pets [38]. We use the standard data augmentation as in Section 4.1. Models are fine-tuned with SGD for 5,000 iterations, following the convention for fine-tuning tasks [4]. To find the best learning rate and weight decay values for each task, we perform a grid search per task and report the best performance. Table 8 shows the results. Note that the ReLabel-trained model results in a consistent improvement over the vanilla pre-trained model. For example, on FGVC Aircraft, ReLabel pre-training improves the downstream task performance by +3.8 pp.

Object detection and instance segmentation. We used Faster-RCNN [41] and Mask-RCNN [15] with feature pyramid network (FPN [31]) as the base models for object detection and instance segmentation tasks, respectively. The backbone networks of Faster-RCNN and Mask-RCNN are initialized with ReLabel-pretrained ResNet-50 model, and then fine-tuned on COCO dataset [32] by the original training strategy [41, 15] with the image size of 1200×800 . Table 9 shows the results. Pre-training with ReLabel improves the bbox AP of Faster-RCNN by +0.5 pp and the mask AP of Mask-RCNN by +0.5 pp. Pre-training a model with cleaner supervision like ReLabel leads to better feature representations and boosts the object detection and instance

	COCO (mAP)
ResNet-50	69.0
ResNet-50 + ReLabel (machine)	72.7
ResNet-50 + ReLabel (oracle)	73.2
ResNet-101	76.6
ResNet-101 + ReLabel (machine)	79.0
ResNet-101 + ReLabel (oracle)	80.9

Table 10. **Originally multi-label tasks.** Results of ReLabel on COCO multi-class classification task [32].

segmentation performances.

4.3. Multi-label Classification

ReLabel is designed to transform a single-label training set into a multi-label training set. Nonetheless, ReLabel and LabelPooling also helps improving an originally multi-label training set by providing additional localized supervision signals, given that the random crop augmentation is a popular recipe for multi-label training as well [5, 55, 59]. To see this effect, we experiment with the multi-label classification dataset COCO [32] with multiple human-annotated labels per image. The baseline multi-label training uses multi-hot annotation $L \in \{0, 1\}^C$ ($C = 80$ for COCO). Instead, we utilize the segmentation ground truth of COCO dataset as label maps $L \in \{0, 1\}^{H \times W \times C}$ (i.e., an oracle case of ReLabel). We also compare with machine-generated label maps $L \in \mathbb{R}^{H \times W \times C}$ from a state-of-the-art multi-label classifier [1] to see the effectiveness of the oracle label map. We then train our multi-label classifiers with our LabelPooling based on the label maps according to the random crop coordinates. We conduct experiments on ResNet-50 and ResNet-101 networks with the input size 224×224 and 448×448 , respectively, using the binary cross-entropy loss for all methods considered. More training details are in Appendix D.3. Table 10 shows the results. We observe that applying ReLabel with machine-generated label maps results in +3.7 pp and +2.4 pp mAP gains and, with oracle label maps, ReLabel achieves more gain of +4.2 pp and +4.3 pp mAP gains on ResNet-50 and ResNet-101 networks, respectively. In summary, the location-wise supervision from ReLabel helps the multi-label classification training.

5. Conclusion

We have proposed a re-labeling strategy, **ReLabel**, for the 1.28 million training images on ImageNet. ReLabel transforms the single-class labels assigned once per image into multi-class labels assigned for every region in an image, based on a machine annotator. The machine annotator is a strong classifier trained on a large extra source of visual data. We also proposed a novel scheme for training a classifier with the localized multi-class labels (**LabelPooling**). We experimentally verified significant performance gains induced by our labels and the corresponding training technique. ReLabel results in a consistent gain across tasks, including the ImageNet benchmarks, transfer-learning tasks, and multi-label classification tasks. We will open-source the localized multi-labels from ReLabel and the corresponding pre-trained models.

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Appendix

A. ReLabel Algorithm

Algorithm A1 ReLabel Pseudo-code

```

1: for each training iteration do
2:   # Load image data and label maps (assume the minibatch size is 1 for simplicity)
3:   input, label_map = get_minibatch(dataset)
4:   # Random crop augmentation
5:   [cx, cy, cw, ch] = get_crop_region(size(input))
6:   input = random_crop(input, [cx, cy, cw, ch])
7:   input = resize(input, [224, 224])
8:   # LabelPooling process
9:   target = RoIAlign(label_map, coords=[cx, cy, cw, ch], output_size=(1, 1))
10:  target = softmax(target)
11:  # Update model
12:  output = model_forward(input)
13:  loss = cross_entropy_loss(output, target)
14:  model_update(loss)
15: end for

```

We present the pseudo-codes of ReLabel in Algorithm A1. We assume the minibatch size is 1 for simplicity. First, an input image and its saved label map are loaded from the dataset. Then the random crop augmentation is conducted on the input image. We then perform RoIAlign on the label map with the random crop coordinates $[c_x, c_y, c_w, c_h]$. Finally softmax function is conducted on the pooled label map to get a multi-label ground-truth in $[0, 1]^C$. The multi-label ground-truth is used for updating the model with the standard cross-entropy loss.

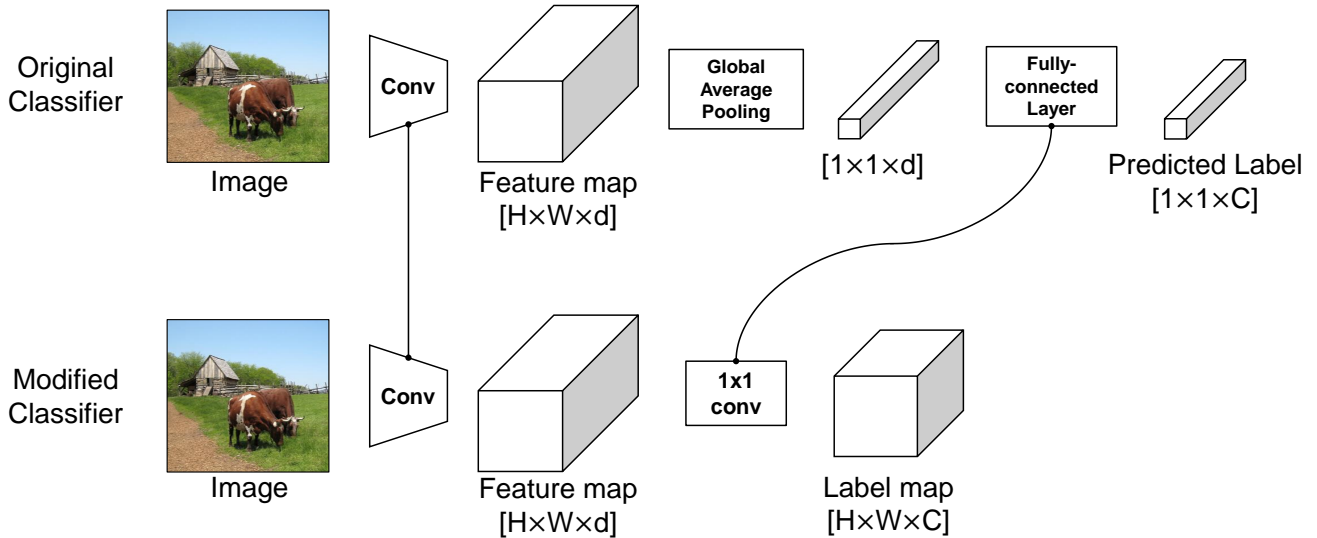


Figure A1. **Obtaining a label map.** The original classifier (upper) takes an input image and generates a predicted label $L_{\text{org}} \in \mathbb{R}^{1 \times 1 \times C}$. On the other hand, the modified classifier (lower) outputs a *label map* $L_{\text{ours}} \in \mathbb{R}^{H \times W \times C}$ by removing the *global average pooling* layer. Note that the “Fully-connected Layer” ($\mathbf{W}_{\text{fc}} \in \mathbb{R}^{d \times C}$) of the original classifier and “ 1×1 conv” ($\mathbf{W}_{1 \times 1 \text{ conv}} \in \mathbb{R}^{1 \times 1 \times d \times C}$) of the modified classifier are identical.

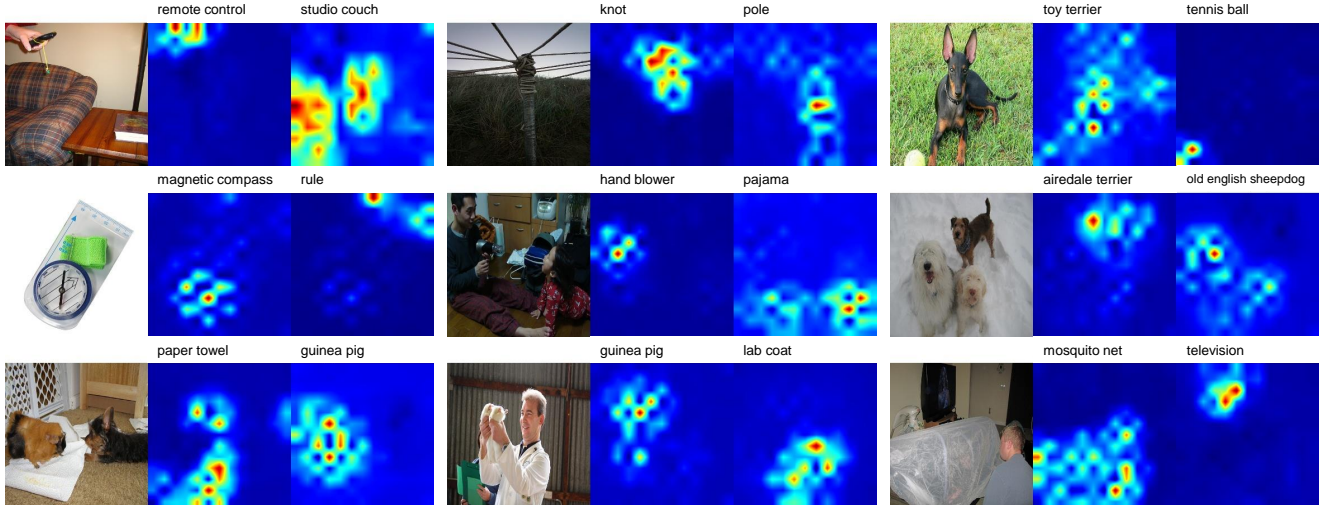


Figure A2. **Label map examples.** Each example presents the input image (left), label map of top-1 class (middle), label map of top-2 class (right).

Network	Supervision	ImageNet	ImageNetV2 (Top-Images)	ImageNetV2 (Matched Frequency)	ImageNetV2 (Threshold 0.7)
ResNet-50	Original	77.5	79.0	65.2	74.3
ResNet-50	Label smoothing ($\epsilon=0.1$) [49]	78.0	79.5	66.0	74.6
ResNet-50	Label cleaning [2]	78.1	79.1	64.9	73.9
ResNet-50	ReLabel	78.9	80.5	67.3	76.0

Table A1. **ImageNetV2 results.** We report performances on ImageNetV2 [40] metrics.

B. Re-labeling ImageNet: Detailed Procedure and Examples

We show the detailed process of obtaining a label map in Figure A1. The original classifier takes an input image, computes the feature map ($\mathbb{R}^{H \times W \times d}$), conducts *global average pooling* ($\mathbb{R}^{1 \times 1 \times d}$), and generates the predicted label $L_{\text{org}} \in \mathbb{R}^{1 \times 1 \times C}$ with the fully-connected layer ($\mathbf{W}_{\text{fc}} \in \mathbb{R}^{d \times C}$). On the other hand, the modified classifier do not have *global average pooling* layer, and outputs a *label map* $L_{\text{ours}} \in \mathbb{R}^{H \times W \times C}$ from the feature map ($\mathbb{R}^{H \times W \times d}$). Note that the fully-connected layer ($\mathbf{W}_{\text{fc}} \in \mathbb{R}^{d \times C}$) of the original classifier and 1×1 conv ($\mathbf{W}_{1 \times 1 \text{ conv}} \in \mathbb{R}^{1 \times 1 \times d \times C}$) of the modified classifier are identical.

We utilize EfficientNet-L2 [56] as our machine annotator classifier whose input size is 475×475 . For all training images, we resize them into 475×475 without cropping and generate label maps by feed-forwarding them. The spatial size of label map (W, H) is (15, 15), number of channel d is 5504, and the number of classes C is 1000.

We present several label map examples in Figure A2. From a label map $L \in \mathbb{R}^{H \times W \times C}$, we only show two heatmaps for the classifier’s top-2 categories. The heatmap is $L[c_i, :, :] \in \mathbb{R}^{H \times W}$ where c_i is one of the top-2 categories. As shown in the examples, the top-1 and top-2 heatmaps are disjointly located at each object’s position.

C. Results on ImageNetV2

We present full ImageNetV2 [40] results in Table A1. Three metrics “Top-Images”, “Matched Frequency”, and “Threshold 0.7” are reported with two baselines Label smoothing [49] and Label cleaning [2]. ReLabel obtained 80.5, 67.3, and 76.0 accuracies on ImageNetV2 “Top-Images”, “Matched Frequency”, and “Threshold 0.7”, where the gains are +1.5, +2.1, and +1.7 pp against the vanilla ResNet-50, respectively.

D. Implementation details

We present the implementation details in this section.

D.1. EfficientNet on ImageNet

We utilize an open-source pytorch codebase [23] to train EfficientNet variants on ImageNet. We utilize AdamP [19] optimizer and set training epochs 400, minibatch size 512, learning rate 0.002, and weight decay 0.01 with four NVIDIA V100 GPUs. Dropout and drop path [25] regularizers are used with dropout rate 0.2 and drop path rate 0.2, respectively. We also utilize Random erasing [63], RandAugment [7], and Mixup [62] augmentations as suggested in [23]. All training settings are samely used for both vanilla training and ReLabel training of EfficientNet variants.

D.2. Knowledge Distillation

Training with knowledge distillation is also conducted on the pytorch codebase [23]. For teacher network, we use official EfficientNet (B1-B7) [50] weights trained with noisy student [56] techniques. We utilize outputs of networks after soft-max layer and the cross-entropy loss between teacher and students is only used for the distillation loss [22]. The temperature and cross-entropy with ground truth were not used. Since the EfficientNet teachers are trained with large-size images ($240 \times 240 - 600 \times 600$), we put the large-size image for teacher network and resize it to 224×224 for inputs of student network. We adopt SGD with Nesterov momentum for the optimizer and the standard setting [16] with long epochs: learning rate 0.1, weight decay 10^{-4} , batch size 256, training epochs 300 and cosine learning rate schedule with four NVIDIA V100 GPUs.

D.3. COCO Multi-label Classification

As in recent multi-label classification works [5, 55, 59, 1], the classifier model is initialized with ImageNet-pretrained model and fine-tuned on COCO multi-label dataset [32]. We utilize the official pytorch ImageNet-pretrained model using torchvision toolbox⁴. The weight of the final fully-connected layer is modified from $\mathbb{R}^{d \times 1000}$ to $\mathbb{R}^{d \times 80}$ to fit the number of classes for COCO dataset and the weight matrix is randomly initialized. For fine-tuning, we utilize AdamP [19] optimizer and cosine learning rate schedule with initial learning rate 0.0002 and weight decay 0.01. We set the minibatch size to 128. The input resolution is 224×224 for ResNet-50 and 448×448 for ResNet-101. To obtain machine-generated label maps, we utilize a pre-trained TResNet-XL model [1] whose input size is 640×640 and mAP is 88.4%.

E. ReLabel Examples on ImageNet

We present ReLabel exsamples on ImageNet training data in Figure A3. We show the full training images (left) and the random cropped patches (right). The random crop coordinates are denoted by blue bounding boxes. We also present the original ImageNet label and the new multi-labels by ReLabel. As shown in the examples, ReLabel can generate location-specific multi-labels with more precise supervision than the original ImageNet label.

⁴<https://github.com/pytorch/vision>



Figure A3. **ReLabel examples during ImageNet training.** We present selected examples generated by ReLabel during ImageNet training. For each example, the left image is the full training image and the right image is the random cropped patch. The random crop coordinates are denoted by blue bounding boxes. The original ImageNet label and ReLabel are also presented.